

Aleta March
amarch2u@hotmail.com
GEOG 375, American River College
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Summary

This project demonstrates the use of a stand-alone Python script to retrieve real-time GeoJSON data from the USGS Earthquake Hazards website and utilize the data to create and export maps showing the location and magnitude of significant earthquakes worldwide.

Purpose

The purpose of this project was to utilize Python and ArcPy scripting to update a cumulative database of global earthquake events using data retrieved from the USGS Earthquake Hazards Program real-time GeoJSON Summary Format Significant Earthquakes feeds and produce and export to PDF format a series of maps comprising:

- 1) a global map of the location of earthquake events that occurred in the time frame of the real-time feed and the time frame of the cumulative database
- 2) local maps of the location of each individual earthquake event that occurred during the time frame (day, week, month) covered by the GeoJSON feed selected by the user.

Data Source

Raw data for this project were obtained from the USGS Earthquake Hazards website <https://earthquake.usgs.gov/earthquake/feed/v1.0/geojson.php> which provides three real-time Significant Earthquake Real-time Feeds updated every minute:

"USGS Significant Earthquakes, Past Day"

https://earthquake.usgs.gov/earthquakes/feed/v1.0/summary/significant_day.geojson

"USGS Significant Earthquakes, Past Week"

https://earthquake.usgs.gov/earthquakes/feed/v1.0/summary/significant_week.geojson

"USGS Significant Earthquakes, Past Month"

https://earthquake.usgs.gov/earthquakes/feed/v1.0/summary/significant_month.geojson

These "GeoJSON Summary Format" feeds use the GeoJSON format, based on the JavaScript Object Notation (JSON) standard, to encode point geographic data structures (Crockford; "GeoJSON").

Methods

Pre-script Requirements

In order for the Python script to function, a file geodatabase must be available to store, query, and manage spatial and non-spatial data ("What is a File Geodatabase?"). Two file geodatabases were created on disk from an ArcGIS Pro 2.4 project: one to handle the cumulative database and feature class located at C:\temp\Final_Project\Data\eq_base.gdb and one to handle in real-time table and feature class located at C:\temp\Final_Project\MyData\eq_output.gdb ("Create a File Geodatabase").

Geoprocessing

Data transformation and information flow from one geoprocess to another was a particularly important aspect of the script. Part I of the script governs the retrieval and extraction of data and management of the tables and feature classes. Part II controls map creation and export.

Part I: Data Management

The information flow begins with the retrieval of the GeoJSON data from the USGS website (Severance 158-160, 163-165; “JSON Encoding”)

```
import json
import urllib.request, urllib.parse, urllib.error
# Open connection "url handle" to URL
urlhand = urllib.request.urlopen(url)
# Read data as bytes and convert to JSON string
data = urlhand.read().decode()
print('Retrieved ', len(data), 'characters')
# Convert (deserialize) JSON string to Python dictionary
jsdata = json.loads(data)
# Convert to JSON string, then "print it pretty" to examine data structure
print(json.dumps(jsdata, indent=4))
```



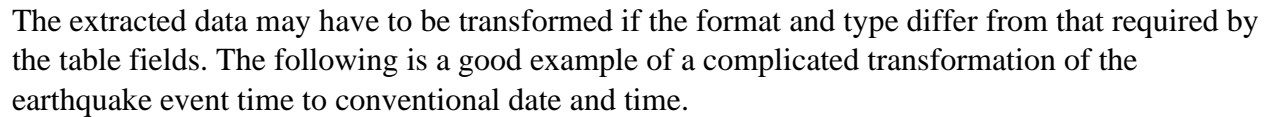
The GeoJSON data is printed out in an easy-to-read format similar to a Python dictionary:

```
{
  "features": [
    {
      "type": "Feature",
      "properties": {
        "mag": 6.3,
        "place": "132km W of Panguna, Papua New Guinea",
      },
      "geometry": {
        "type": "Point",
        "coordinates": [
          154.3008,
          -6.5105,
          16.85
        ]
      },
      "id": "us60009c06"
    },
  ],
}
```











Next, the data is extracted using indexing:

- magnitude = entry[['properties']]['mag']
- place = entry[['properties']]['place']
- lon = entry[['geometry']]['coordinates'][0]
- lat = entry[['geometry']]['coordinates'][1]



Let the Geoprocessing Begin!











Field:    Selection:     

OBJECTID	USGS_ID	Date	Event_Time	Magnitude	Place	Lon	Lat	Depth	Update_Time
Click to add new row.									



eq_out_table eq_base_table X

Field:  Add  Delete  Calculate Selection:  Zoom To  Switch  Clear  Delete  Copy

OBJECTID	USGS_ID	Date	Event_Time	Magnitude	Place	Lon	Lat	Depth	Update_Time
Click to add new row.									

InsertCursor
InsertRow



Populated Real-time Output Table

OBJECTID	USGS_ID	Date	Event_Time	Magnitude	Place	Lon	Lat	Depth	Update_Time
1	c38488354	2020-05-10	22:07:40.370000	4.54	17km SE of Ocotillo Wells,	-116.0202	33.01833	10.16	1589214000000
2	us70009b14	2020-05-06	13:53:56.960000	6.8	205km NW of Saumlaki, In.	129.8613	-6.7949	107	1589069000000

arcpy.MakeTableView_management
arcpy.management.XYTableToPoint



Populated Real-time Feature Class

OBJECTID	Shape	USGS_ID	Date	Event_Time	Magnitude	Place	Lon	Lat	Depth	Update_Time
1	Point	c38488354	2020-05-10	22:07:40.370000	4.54	17km SE of Ocotillo Wells, CA	-116.0202	33.01833	10.16	1589214000000
2	Point	us70009b14	2020-05-06	13:53:56.960000	6.8	205km NW of Saumlaki, Indonesia	129.8613	-6.7949	107	1589069000000

arcpy.da.SearchCursor
arcpy.da.UpdateCursor



Base Table with Updated Rows

```
with arcpy.da.SearchCursor(eq_out_tbl_path, field_list) as srows:
    with arcpy.da.UpdateCursor(base_table, field_list) as uprows:
        search_loop_counter = 0 #Shows current cycle of search loop through real-time feed table

        for srow in srows: # Assign search row field values used for comparison
            rt_feed_id = srow[0] # USGS_ID field value
            rt_feed_updated = srow[8] # Update_Time field value
            print('Search loop cycle', search_loop_counter)

            if base_row_count > 0: # If base table filled, compare entries with real-time feed entries
                for uprow in uprows:
                    found = False
                    # Set field values to be compared
                    base_id = uprow[0]
                    base_updated = uprow[8]

                    if base_id == rt_feed_id: # If a match is found
                        found = True

                        # Check if more recent update available; update base table if so
                        if base_updated < rt_feed_updated:
                            uprows.updateRow(srow)
                            print(base_id, 'base table updated')

                        # Add event row values to updated_event_rows list
                        updated_event_rows.append(srow)
                        print('USGS_ID', rt_feed_id, 'row values added to updated_event_rows list')

                # If match found, end search
                if found == True:
                    uprows.reset() # Cursor reset to first row for next loop
                    print('Break out of loop') # Avoid unnecessary further search
                    break

            if found == False or base_row_count == 0: # If match not found in permanent db or db empty
                print('Event not found in permanent database.')
                # Add to end of list
                new_event_rows.append(srow)
                print('USGS_ID', rt_feed_id, 'event row values added to new_event_rows list')
                print(srow)
                uprows.reset()

        search_loop_counter = search_loop_counter + 1
```



Produces Two Lists of Row Tuples

updated_event_rows

new_event_rows

These lists are key to the remainder script. They contain the values of rows that will be updated or added to the base table and feature class.

arcpy.da.InsertCursor
InsertRow



Base Feature Table with New Event Rows Added

Sample Row Tuple

('us70008jr5', '2020-03-31', '23:52:31.094000', 6.5,
'72km W of Challis, Idaho', -115.1355972290039,
44.46030044555664, 14.529999732971191, 1587859423232.0)

[Create base feature class
if it does not exist using
arcpy.management.XYTableToPoint]



Base Feature Class

OBJECTID	Shape	USGS_ID	Date	Event_Time	Magnitude	Place	Lon	Lat	Depth	Update_Time
1		us70008jr5	2020-03-31	23:52:31.094000	6.5	72km W of Challis, Idaho	-115.1355972290039	44.46030044555664	14.529999732971191	1587859423232.0

arcpy.da.UpdateCursor
UpdateRow



Base Feature Class with Updated Rows

Sample Row Tuple

([-115.1355972290039, 44.46030044555664], 'us70008jr5', '2020-03-31',
'23:52:31.094000', 6.5, '72km W of Challis, Idaho', -115.1355972290039,
44.46030044555664, 14.529999732971191, 1587859423232.0)

NOTE: inserting or updating a row in a feature class is different than in a table because a geometry must be written.

- 1) The field list must include the 'Shape' field in the initial position
- 2) The 'SHAPE@XY' geometry token may be used in place of 'Shape' in the field list
- 3) The row tuple to be inserted must have a Point value tuple (lon, lat) in the initial position to populate the 'Shape' field (see highlighted tuple above).

```
# Create update cursor for base feature class; replace 'Shape' field with 'SHAPE@XY' to add 'Point' geometry
with arcpy.da.UpdateCursor(base_fc, ['SHAPE@XY', 'USGS_ID', 'Date', 'Event_Time', 'Magnitude', 'Place', 'Lon', 'Lat', 'Depth', 'Update_Time']) as uprows:
    index = 0 #Counter for rows to be updated

    for uprow in uprows:

        for index in range(0, total_updates):
            # If USGS_ID in base_fc matches the ID in the tuple of the updated_event_rows list, then update row
            if uprow[1] == updated_event_rows[index][0]:
                # Create new tuple with xy point value as first element (needed to add Point geometry to 'Shape' field)
                xy = (updated_event_rows[index][5], updated_event_rows[index][6]) # tuple represents (Lon, Lat) values

                # Create new update row tuple by appending the row elements of updated_event_rows to xy geometry tuple
                new_tup = (xy,)

                for i in range(0, 9):
                    new_tup = new_tup + (updated_event_rows[index][i],)

                # Update row of base_feature class with element (tuple) of new_tup
                uprows.updateRow(new_tup)
                print('Updated row in base feature class', new_tup, '\n')

del uprow
del uprows
```

arcpy.da.InsertCursor
InsertRow



Base Feature Class with New Event Rows Added

```
((-85.70989990234375, 16.93320083618164), 'us70008xeb', '2020-04-16',  
'08:04:37.597000', 6.0, '55km NNE of Savannah Bight, Honduras',  
-85.70989990234375, 16.93320083618164, 10.0, 1587751813120.0)
```

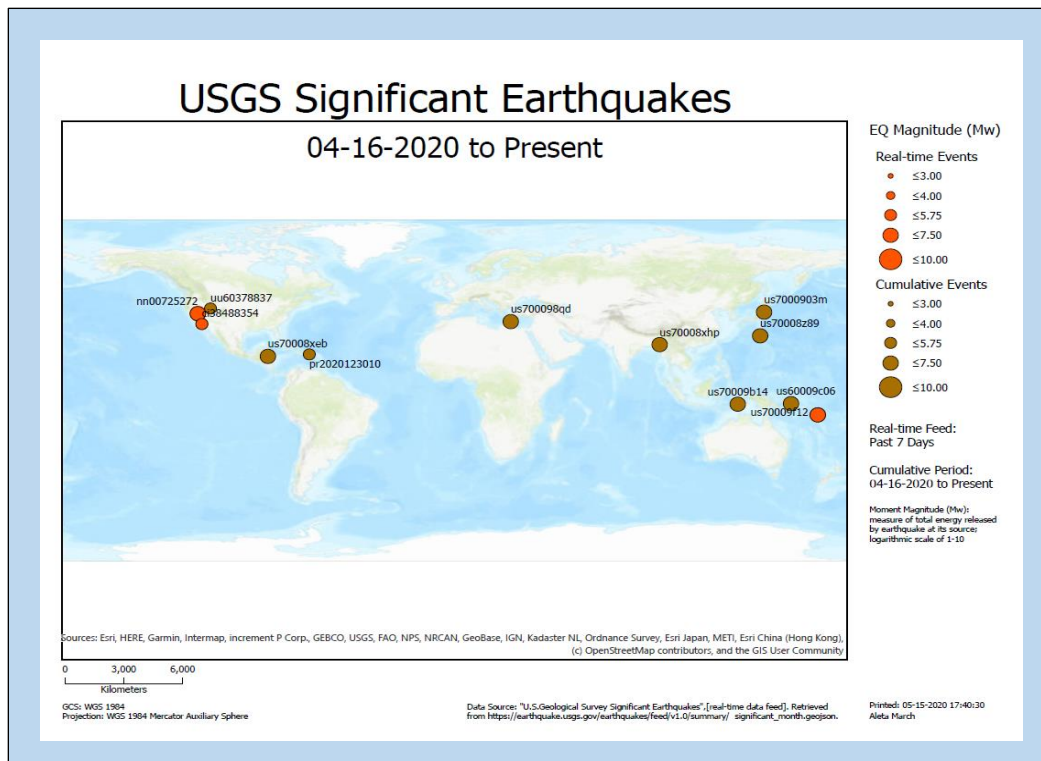
Part II: Map Creation and Export

This segment of the script is responsible for the production and export of maps showing the location of earthquake events.

Output maps are variations of two types, global and local:

- 1) one global map at full map extent showing the cumulative base layer overlaid by the real-time layer produced by the 1, 7, or 30-day real-time feed) with graduated point symbols based on earthquake event magnitude
- 2) a group of local maps equivalent to the number of real-time events. Individual maps each show a zoomed-in view of one real-time event, along with any previous events within the map frame extent.

Geoprocessing is scant in this section. The arcpy.mp module is used to modify existing layout elements, visibility of map frame layers, and map frame extents prior to the export of maps in PDF format. The global map is printed at the full geographic extent of the base map.

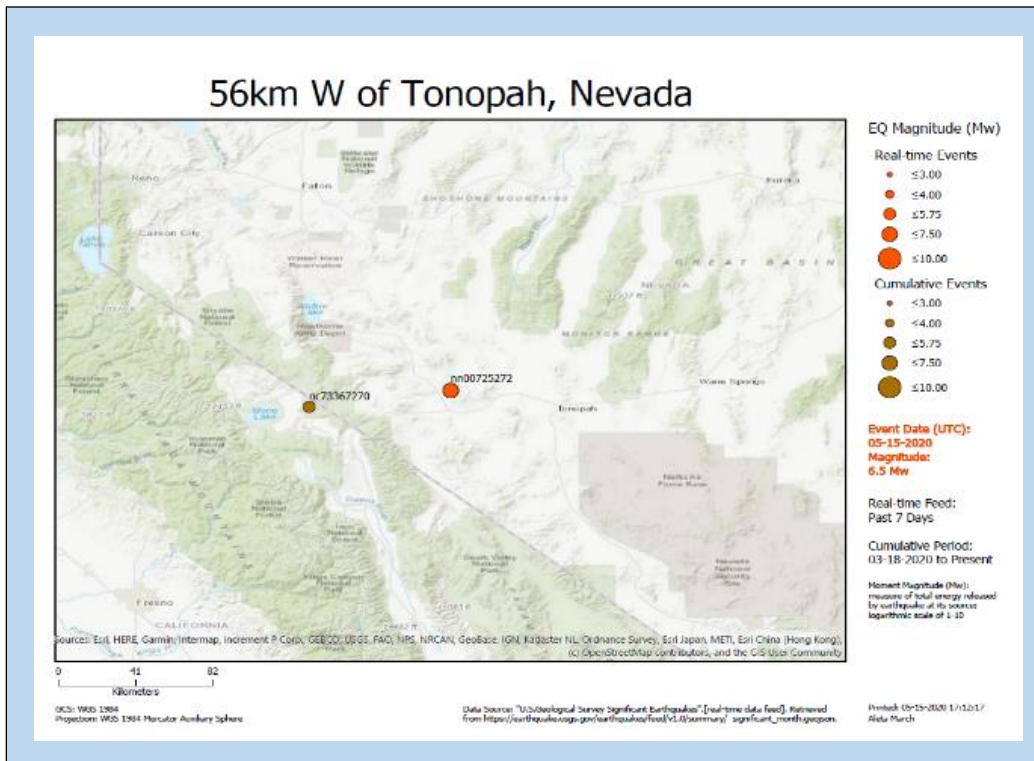


A multi-step process is required to perform a zoom-in effect on an individual real-time event. First, `SelectByAttribute` with a selection query produces a subset of the real-time layer and `GetExtent` returns a derived extent (“Zoom Map”). Extent and scale of the map frame is then controlled by the Camera object, mimicking zooming-in to a feature (“Camera”).

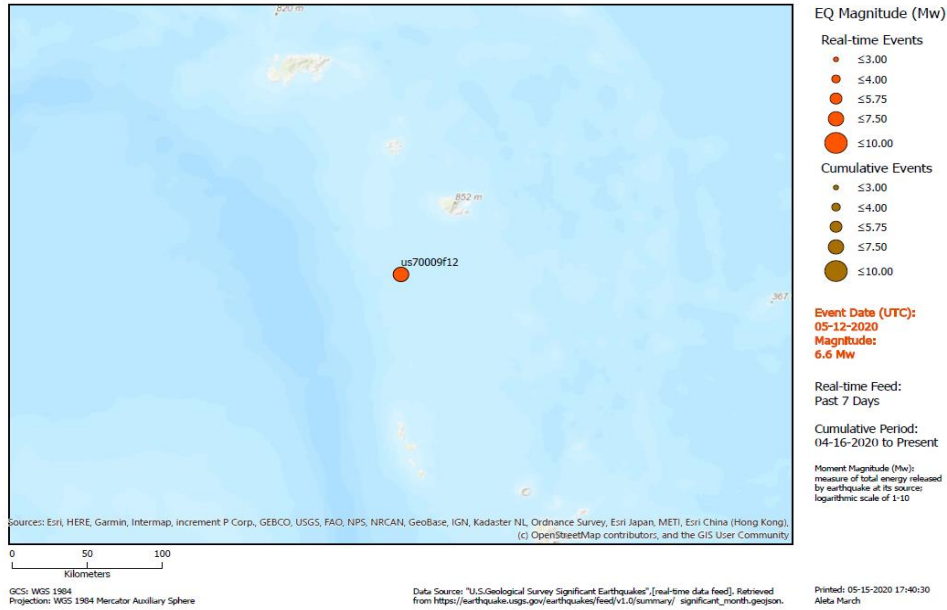
```
# Select current row for definition query
query = """"USGS_ID" = '""" + rt_USGS_ID + """"""
arcpy.SelectLayerByAttribute_management(rt_lyr, "NEW_SELECTION", query)
rt_lyr.definitionQuery = query
print(rt_USGS_ID, 'selected to map')

# Get/Set layerExtent for selected row
layer_extent = mapframe.getLayerExtent(rt_lyr, True, True)
print('Layer extent rt_layer:' + str(layer_extent))

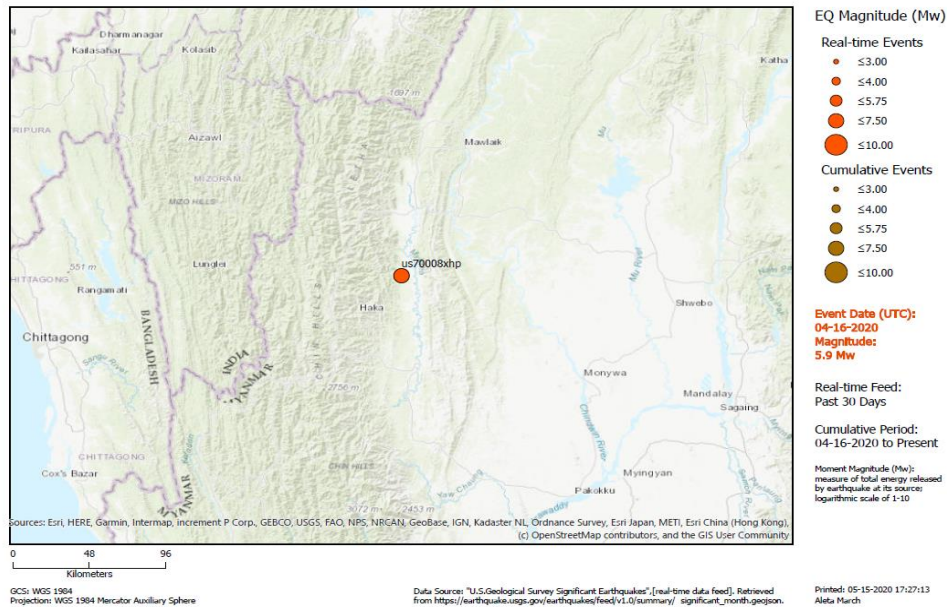
# Set mapframe camera to layer extent
mapframe.camera.setExtent(layer_extent)
# Set mapframe scale (create zoom-in effect)
mapframe.camera.scale = 2400000.00
```



173km SSE of Lata, Solomon Islands



38km ESE of Falam, Burma



Challenges / Solutions

Much of the basic geoprocessing code related to the use of insert, search, and update cursors, selection queries, and map production was taken directly from the video lectures given by Professor Jennings this semester (Jennings, Video Lectures) and from the workbooks he authored (Jennings, *Python Primer 1, 2, 3*). Early in the process of creating the script, I relied heavily on these coding templates, to the point of using some of the same variable names, until I gained familiarity with the concepts. As I progressed in my learning, I was able to customize and build on these scripts, incorporating additional processes using original code.

Many programming issues resulted from my inexperience using Python and were eventually overcome. One problem that was resolved after considerable effort pertained to the use of the geometry token 'SHAPE@XY' when adding a feature to a feature class ("How To: Add Features"). Silver lining: it gave me the opportunity to post something on GeoNet ("Add Row").



Aleta March

Apr 30, 2020 11:45 AM

★ Correct Answer

Hello All,

My problem has been resolved. I was trying to use the geometry tokens ('SHAPE@X' and 'SHAPE@Y') to replace the fields containing the floating point X and Y values for 'Lon' and 'Lat'. Wrong tokens and wrong fields!

By 1) using the 'SHAPE@XY' token instead of the 'Shape' field name in the arcpy.da.InsertCursor field list and 2) populating that field with a tuple containing the (Lon, Lat) values, the Point geometry is added.

It seems so simple now, but as a newcomer to ArcPy, it wasn't clear to me that the 'Shape' field that, to my eye, contained values in the feature class table that looked like the string 'Point', needed to be filled with a tuple of floating point numbers. Lesson learned.

Aleta March

At the conclusion of the project, three problems remained unresolved. The first two issues are related to basic ArcPy programming concepts and the third may be specific to either the input data format or the program logic. In addition, a deficiency with respect to exception code was noted.

PROBLEM 1: Unable to Control the Position of Rows Inserted into a Table

As a consequence of the manner in which the `arcpy.da.InsertCursor` and `InsertRow` functions operate, new rows are inserted at the bottom of a table. This results in the creation of the cumulative base table with the oldest event at the top of the table and the newest event at the bottom, preserving the order of the table as it accumulates rows. The disadvantage is that it increases the time it takes to search the existing base table, to determine the necessity of an event addition or update. As the base table accumulates more rows, the search time will become increasingly longer. If the order were reversed, the comparison of the real-time events with the most recent events in the base table would be more efficient.

In my hunt for a solution, I tried to find a way to add a row to the top of the table or to begin a search at the bottom of the table. My attempts to find an elegant solution were futile. Perhaps, due to inexperience, my viewpoint was so narrow that I could not recognize the alternatives.

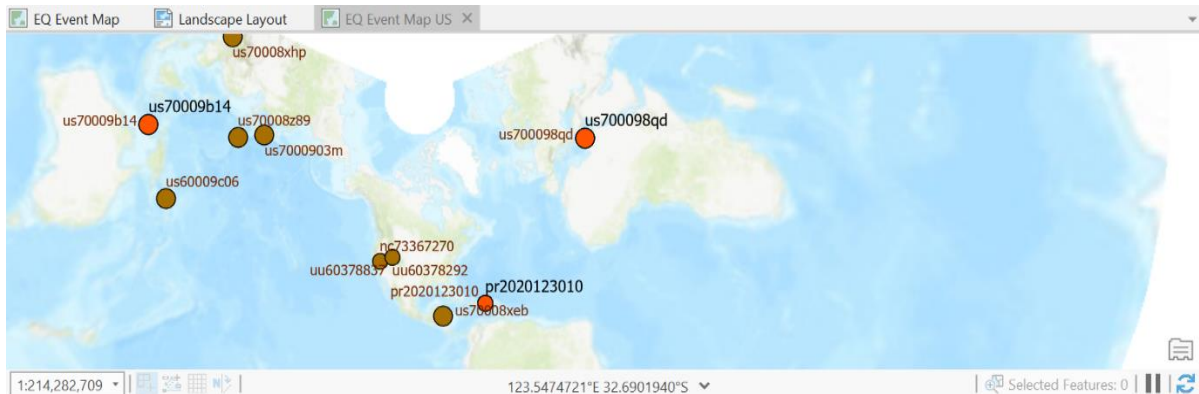
PROBLEM 2: Unable to Change Spatial Reference of Mapframe

It was my original intent to customize the spatial reference of the exported maps of individual events according to their geographic location and extent. Unfortunately, I was unable to do so, resulting in all maps being produced with WGS 1984 geographic coordinate system and WGS 1984 Mercator Auxiliary Sphere projection.

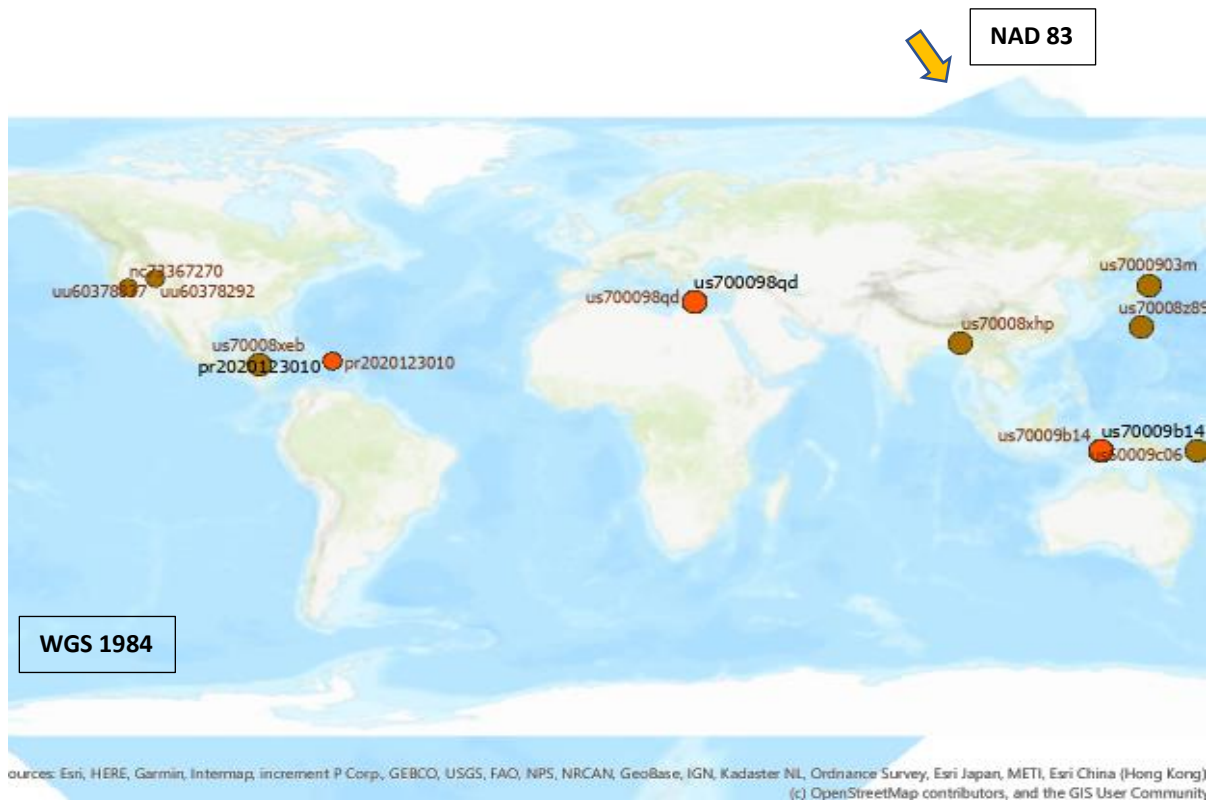
It is my understanding that `arcpy.mp` does not yet provide a way to change the spatial reference of mapframes or maps (“Allow `arcpy.mp` to Modify”). According to Jeff Barrette of the ESRI `arcpy.mp` team, that functionality will be available with ArcGIS Pro 2.6.

A potential workaround would be to make several maps within the ArcGIS Pro project, each with a different spatial reference and set up one layout to contain multiple mapframes. The Python script would then be used to select and make visible only the mapframe with the appropriate spatial reference for the extent of the exported map.

Pursuing this workaround proved beyond the time constraints of this project. I was able, however, to create one additional test map with a spatial reference of NAD 83 / USA Contiguous Lambert Conformal Conic, as shown below.



The corresponding mapframe was then added as a mapframe to the common layout, stacked below the original mapframe.



PROBLEM 3: Point Features Occasionally Missing from a Map

I have been unable to explain the infrequent (two occurrences) of a point feature missing from a map. The data format of the GeoJSON input data matches that of the extracted data output. There were no discernable differences between the rows of the faulty point features and the others.



DEFICIENCY: Custom Exception Code Not Included

Other than the Try:/Except statement surrounding the script, custom exception code was not created for the script (Jennings, “Demo 6D”). Custom exception code designed to handle errors caused by a faulty Internet connection or a request timing out would have been beneficial. The rare instances that triggered the runtime error, “Not signed into Portal”, were due to an unstable or absent Internet connection. This was verified by intentionally turning off the Internet hotspot and running the script to re-create the error message. Although I did some preliminary research on the `urllib.request` and `urllib.error` submodules, I did not feel that I had sufficient knowledge to create the code required to raise a connection or timeout exception (“`urllib.error`”; “`urllib.request`”).

Conclusion

This project has helped to change my perspective on programming for GIS. Prior to taking this course, I thought using Python was all about coding syntax and logic and troubleshooting and frustration. Well, it is, but it is also so much more! It involves knowing your data and understanding how the software for which you are coding functions “under the hood”. I know that I have barely scratched the surface, but even this little bit of knowledge has given me a lot of power to learn more. It has been a long journey from printing “Hello World!” back in January.

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